

# Conservative SPDEs as fluctuating mean field limits of stochastic gradient descent

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GPSD 2023 — Essen

joint work with Benjamin Gess and Rishabh Gvalani



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- 1 Derivation of SPDE and application in Machine Learning
- 2 Well-posedness, superposition principle and connection with SGD dynamics

# Supervised Learning

- Having a large sets of data  $\{(\theta_i, \gamma_i), i \in I\}$ , one needs to find a function  $f : \Theta \rightarrow \mathbb{R}$  such that  $f(\theta_i) = \gamma_i$ .

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- Usually one approximates  $f$  by

$$f_n(\theta) = \frac{1}{n} \sum_{k=1}^n U(\theta, x_k),$$

where  $x_k \in \mathbb{R}^d$ ,  $k \in \{1, \dots, n\}$ , are parameters which have to be found.  
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- We measure the distance between  $f$  and  $f_n$  by the **generalization error**

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# Stochastic Gradient Descent and (deterministic) PDE

The parameters  $x_k$ ,  $k \in \{1, \dots, n\}$ , can be learned by stochastic gradient descent

$$x_k(t_{i+1}) = x_k(t_i) - \nabla_{x_k} |f(\theta_i) - f_n(\theta_i; x)|^2 \Delta t$$

where  $\Delta t$  is a **learning rate**,  $t_i = i\Delta t$ ,  $\{\theta_i, i \in \mathbb{N}\}$  are i.i.d. with distribution  $m$ ,

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 &= x_k(t_i) + V(x_k(t_i), \nu_{t_i}^n, \theta_i) \Delta t
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If  $x_k(0)$  are i.i.d. from  $\mu_0$ , then

$$d(\nu_t^n, \mu_t) = O(n^{-1/2}) + O(\Delta t^{1/2}) = O(n^{-1/2}), \quad \text{for } \Delta t = \frac{1}{n},$$

where  $\mu_t$  solves

$$d\mu_t = -\nabla (V(\cdot, \mu_t)\mu_t) dt$$

with  $V(x, \mu) = \mathbb{E}_m V(x, \mu, \theta)$ .

[Mei, Montanarib, Nguyen, 2018]

# Main Goal

**Problem.** After passing to the limit the equation

$$d\mu_t = -\nabla (V(\cdot, \mu_t)\mu_t) dt$$

loses the information about the fluctuations of the SGD dynamics

$$x_k(t_{i+1}) = x_k(t_i) + V(x_k(t_i), \nu_{t_i}^n, \theta_i)\Delta t, \quad \nu_t^n = \frac{1}{n} \sum_{l=1}^n \delta_{x_l(t)}.$$

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**Goal:** Propose a **stochastic** PDE which would capture the fluctuations of the SGD dynamics. Then, probably, its solutions would better approximate the SGD dynamics as  $n \rightarrow \infty$  and  $\Delta t \rightarrow 0$ .

# SGD and Martingale Problem (standard approach)

Stochastic gradient descent

$$\begin{aligned}x_k(t_{i+1}) &= x_k(t_i) + V(x_k(t_i), \nu_{t_i}^n, \theta_i) \Delta t \\ &= x_k(t_i) + V(x_k(t_i), \nu_{t_i}^n) \Delta t + \sqrt{\Delta t} (V(x_k(t_i), \nu_{t_i}^n, \theta_i) - V(x_k(t_i), \nu_{t_i}^n)) \sqrt{\Delta t}\end{aligned}$$

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is the Euler-Maruyama scheme for the SDE

$$\begin{aligned}dx_k(t) &= V(x_k(t), \mu_t^n) dt + \sqrt{\alpha} dB_k(t), \quad k \in \{1, \dots, n\} \\ d[B_k, B_l]_t &= A(x_k(t), x_l(t), \mu_t^n) dt,\end{aligned}$$

where  $\mu_t^n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i(t)}$  and  $A(x, y, \mu) = \mathbb{E}_m G(x, \mu, \theta) \otimes G(y, \mu, \theta)$ .

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$$d\mu_t^n = \frac{\alpha}{2} \nabla^2 : (A(\cdot, \mu_t^n) \mu_t^n) dt - \nabla \cdot (V(\cdot, \mu_t^n) \mu_t^n) dt + \nabla \cdot \sqrt{\alpha} dW^{\text{cor}}(\cdot, t),$$

with  $[dW^{\text{cor}}(x, t), dW^{\text{cor}}(y, t)] = A(x, y, \mu_t^n) \mu_t^n(x) \mu_t^n(y)$ .

[Rotskoff, Vanden-Eijnden, CPAM, 2022]



# SGD and SPDE (new approach)

Stochastic gradient descent

$$x_k(t_{i+1}) = x_k(t_i) + V(x_k(t_i), \nu_{t_i}^n) \Delta t + \sqrt{\alpha} G(x_k(t_i), \nu_{t_i}^n, \theta_i) \sqrt{\Delta t},$$

where  $\nu_t^n = \frac{1}{n} \sum_{l=1}^n \delta_{x_l(t)}$ ,  $\alpha = \Delta t$ ,  $G(x, \mu, \theta) = V(x, \mu, \theta) - V(x, \mu)$  and  $\theta_i$  are i.i.d. with distribution  $m$  on  $\Theta$ .

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We take a cylindrical Wiener process  $W$  on  $L_2(\Theta, \mathfrak{m})$  and consider the equation

$$dX(u, t) = V(X(u, t), \mu_t) dt + \sqrt{\alpha} \int_{\Theta} G(X(u, t), \mu_t, \theta) W(d\theta, dt),$$

$$X(u, 0) = u, \quad \mu_t = \mu_0 \circ X^{-1}(\cdot, t), \quad u \in \mathbb{R}^d, \quad t \geq 0.$$

[Kotelenez '95, Dorogotsev, Wang '21]

(See [Gess, Kassing, K. '23] for further connection with SDG dynamics)

# Stochastic Mean-Field Equation

Applying Itô 's formula to  $\langle \varphi, \mu_t \rangle$ , we come to the **Stochastic Mean-Field Equation (SMFE)**:

$$d\mu_t = \frac{\alpha}{2} \nabla^2 : (A(\cdot, \mu_t) \mu_t) dt - \nabla \cdot (V(\cdot, \mu_t) \mu_t) dt + \sqrt{\alpha} \nabla \cdot \int_{\Theta} G(\cdot, \mu_t, \theta) \mu_t W(d\theta, dt)$$

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For comparison:

$$d\mu_t = \frac{\alpha}{2} \nabla^2 : (A(\cdot, \mu_t) \mu_t) dt - \nabla \cdot (V(\cdot, \mu_t) \mu_t) dt + \nabla \cdot \sqrt{\alpha} dW^{\text{cor}}(\cdot, t),$$

with  $[dW^{\text{cor}}(x, t), dW^{\text{cor}}(y, t)] = A(x, y, \mu_t) \mu_t(x) \mu_t(y)$  and  $A = \mathbb{E}_m G \otimes G$ .  
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↪ Both solutions satisfy the same martingale problem!

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1 Derivation of SPDE and application in Machine Learning

2 Well-posedness, superposition principle and connection with SGD dynamics

# Related Works to SMFE

$$d\mu_t = \frac{1}{2} \nabla^2 : (A(\cdot, \mu_t) \mu_t) dt - \nabla \cdot (V(\cdot, \mu_t) \mu_t) dt - \nabla \cdot \int_{\Theta} (G(\cdot, \mu_t, \theta) \mu_t) W(d\theta, dt),$$

Well-posedness results for similar SPDEs:

- **Continuity equation in the fluid dynamics and optimal transportation** [Ambrosio, Trevisan, Crippa. . .]. There  $A = G = 0$ .

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- **Stochastic nonlinear Fokker-Planck equation** [Coghi, Gess '19]. The covariance  $A$  has more general structure but the noise is **finite-dimensional**.
- **Particle representations for a class of nonlinear SPDEs** [Kurtz, Xiong '99]. The equation has more general form but the **initial condition  $\mu_0$  must have an  $L_2$ -density** w.r.t. the Lebesgue measure.

# Well-posedness of SMFE

## Theorem (Gess, Gvalani, K. 2022)

Let the coefficients  $V, G$  be Lipschitz continuous and smooth enough w.r.t. spetal variable. Then the SMFE

$$d\mu_t = \frac{\alpha}{2} \nabla^2 : (A(\cdot, \mu_t) \mu_t) dt - \nabla \cdot (V(\cdot, \mu_t) \mu_t) dt \\ - \sqrt{\alpha} \nabla \cdot \int_{\Theta} G(\cdot, \mu_t, \theta) \mu_t W(d\theta, dt)$$

has a unique solution. Moreover,  $\mu_t$  is a **superposition solution**, i.e.,

$$\mu_t = \mu_0 \circ X^{-1}(\cdot, t), \quad t \geq 0,$$

where  $X$  solves

$$dX(u, t) = V(X(u, t), \mu_t) dt + \sqrt{\alpha} \int_{\Theta} G(X(u, t), \mu_t, \theta) W(d\theta, dt), \quad X(u, 0) = u.$$

# Convergence to deterministic PDE

## Theorem (Gess, Gvalani, K. 2022)

Let  $\mu^{n, \frac{1}{n}}$  be superposition solutions to the SMFE ( $\alpha = \frac{1}{n}$ )

$$d\mu_t = \frac{1}{2n} \nabla^2 : (A(\cdot, \mu_t) \mu_t) dt - \nabla \cdot (V(\cdot, \mu_t) \mu_t) dt \\ - \frac{1}{\sqrt{n}} \nabla \cdot \int_{\Theta} G(\cdot, \mu_t, \theta) \mu_t W(d\theta, dt),$$

started from  $\mu_0^{n, \frac{1}{n}} = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$  with  $x_i \sim \mu_0$  i.i.d. Then

$$\mathbb{E} \sup_{t \in [0, T]} \mathcal{W}_2^2(\mu_t^{n, \frac{1}{n}}, \mu_t^0) \leq Cn^{-1},$$

and  $d\mu_t^0 = -\nabla \cdot (V(\cdot, \mu_t^0) \mu_t^0) dt$ .

# Quantified CLT for SMFE

Since  $\mu_t^{n, \frac{1}{n}} = \mu_t^0 + O(n^{-1/2})$ , we consider

$$\eta_t^n = \sqrt{n} \left( \mu_t^{n, \frac{1}{n}} - \mu_t^0 \right).$$

## Theorem (Gess, Gvalani, K. 2022)

There exists the Gaussian fluctuation field  $\eta$ , which is a solution to the linear SPDE

$$\begin{aligned} d\eta_t = & -\nabla \cdot \left( V(\cdot, \mu_t^0) \eta_t + \langle \tilde{V}(x, \cdot), \eta_t \rangle \mu_t^0(dx) \right) dt \\ & - \nabla \cdot \int_{\Theta} G(\cdot, \mu_t^0, \theta) \mu_t^0 W(d\theta, dt). \end{aligned}$$

Moreover,

$$\mathbb{E} \sup_{t \in [0, T]} \|\eta_t^n - \eta_t\|_{H^{-j}}^2 \leq Cn^{-1}.$$

# Higher order approximation of the SGD dynamics

The quantified CLT gives us that

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The empirical distribution of SGD with  $n$  parameters and learning rate  $\alpha = \frac{1}{n}$  satisfies

$$\nu_t^{n, \frac{1}{n}} = \frac{1}{n} \sum_{i=1}^n \delta_{x_i(\lfloor nt \rfloor)} = \mu_t^0 + n^{-1/2} \eta_t + o(n^{-1/2})$$

[Sirignano, Spiliopoulos, SPA, 2020]

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Therefore,  $\nu_t^{n, \frac{1}{n}} - \mu_t^{n, \frac{1}{n}} = o(n^{-1/2})$ .

# Higher order approximation of the SGD dynamics

## Theorem (Gess, Gvalani, K. 2022)

Let  $\mu^{n, \frac{1}{n}}$  be a superposition solution to the SMFE with learning rate  $\alpha = \frac{1}{n}$  started from  $\frac{1}{n} \sum_{i=1}^n \delta_{x_i}$ . Let also  $\nu^{n, \frac{1}{n}}$  be the empirical process associated to the SGD dynamics with  $\alpha = \frac{1}{n}$ . Then

$$\mathcal{W}_p \left( \text{Law}(\mu^{n, \frac{1}{n}}), \text{Law}(\nu^{n, \frac{1}{n}}) \right) = o(n^{-1/2})$$

for all  $p \in [1, 2)$ .



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**Remark.** The SMFE

$$d\mu_t = \frac{1}{2} \nabla^2 : (A(\cdot, \mu_t) \mu_t) dt - \nabla \cdot (V(\cdot, \mu_t) \mu_t) dt - \nabla \cdot \int_{\Theta} G(\cdot, \mu_t, \theta) \mu_t W(d\theta, dt)$$

captures the fluctuations of the SGD dynamics. Therefore, it gives a better approximation of the SGD dynamics than

$$d\mu_t = -\nabla \cdot (V(\cdot, \mu_t) \mu_t) dt$$

# Reference



Gess, Gvalani, Konarovskiy,

Conservative SPDEs as fluctuating mean field limits of stochastic gradient descent

(arXiv:2207.05705)



Gess, Kassing, Konarovskiy,

Stochastic Modified Flows, Mean-Field Limits and Dynamics of Stochastic Gradient Descent

(arXiv:2302.07125)

# Thank you!