

Sticky-reflected stochastic heat equation driven by colored noise

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Sticky-reflected stochastic heat equation on $[0, 1]$

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \lambda \mathbb{I}_{\{X_t=0\}} + \mathbb{I}_{\{X_t>0\}} \dot{W}_t$$

$$X_0 = g \geq 0, \quad X_t(0) = X_t(1) = 0$$

where $\lambda > 0$

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where $\lambda > 0$

It is similar to the SDE for sticky-reflected Brownian motion:

$$\begin{aligned} dx(t) &= \lambda \mathbb{I}_{\{x(t)=0\}} dt + \mathbb{I}_{\{x(t)>0\}} dw(t), \\ x(0) &= x_0 \geq 0 \end{aligned}$$

– only weak existence and uniqueness in law! (Engelbert and Peskir, 2014)

Reason of investigation

- Sticky-reflected SHE vs. Reflected SHE (Nulart and Pardoux, 1992)

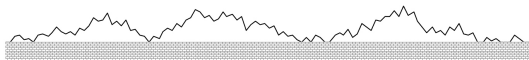
$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \delta_0(X_t) + \dot{W}_t$$

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- A new method of solving SDEs with discontinuous coefficients.

Formulation of the main result

Sticky-reflected SHE:

$$\begin{aligned}\frac{\partial X_t}{\partial t} &= \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \lambda \mathbb{I}_{\{X_t=0\}} + \mathbb{I}_{\{X_t>0\}} \dot{W}_t \\ X_0 &= g \geq 0, \quad X_t(0) = X_t(1) = 0,\end{aligned}$$

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Solution to sticky-reflected SHE

A continuous process $X : [0, \infty) \times [0, 1] \rightarrow \mathbb{R}$ is called a **weak solution** to the sticky-reflected SHE if for any $\varphi \in C^2[0, 1]$ with $\varphi(0) = \varphi(1) = 0$

$$M_t^\varphi := \langle X_t, \varphi \rangle - \langle X_0, \varphi \rangle - \frac{1}{2} \int_0^t \langle X_s, \varphi'' \rangle ds - \int_0^t \langle \lambda \mathbb{I}_{\{X_s=0\}}, \varphi \rangle ds$$

is a martingale with quadratic variation

$$[M^\varphi]_t = \int_0^t \|Q(\mathbb{I}_{\{X_s>0\}}\varphi)\|_{L_2}^2 ds.$$

Formulation of the main result

Let $\{e_k, k \geq 1\}$ and $\{\mu_k, k \geq 1\}$ be eigenvectors and eigenvalues of Q . Define

$$\chi^2 := \sum_{k=1}^{\infty} \mu_k^2 e_k^2.$$

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Theorem

If $\chi^2 > 0$ a.e., then the sticky-reflected SHE admits a weak solution.

Meaning of assumption $\chi^2 > 0$

The equation

$$\begin{aligned} dx(t) &= \lambda \mathbb{I}_{\{x(t)=0\}} dt \\ x(0) &= 0 \end{aligned}$$

has **no solution**

Meaning of assumption $\chi^2 > 0$

The equation

$$\begin{aligned} dx(t) &= \lambda \mathbb{I}_{\{x(t)=0\}} dt + \mathbb{I}_{\{x(t)>0\}} dw(t) \\ x(0) &= 0 \end{aligned}$$

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has ~~no solution~~ a weak solution

$\chi^2 = \sum_{k=1}^{\infty} \mu_k^2 e_k^2 > 0$ means that the solution X to the equation

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \lambda \mathbb{I}_{\{X_t=0\}} + \mathbb{I}_{\{X_t>0\}} Q \dot{W}_t$$

feels a noise at **any** point of $[0, 1]$.

Description of the idea of construction of solution
using the equation

$$dx(t) = \lambda \mathbb{I}_{\{x(t)=0\}} dt + \mathbb{I}_{\{x(t)>0\}} dw(t)$$

Approximating sequence

Consider the SDE for sticky-reflected BM:

$$dx(t) = \lambda \mathbb{I}_{\{x(t)=0\}} dt + \mathbb{I}_{\{x(t)>0\}} dw(t),$$

$$x(0) = x_0 \geq 0.$$

Approximating sequence

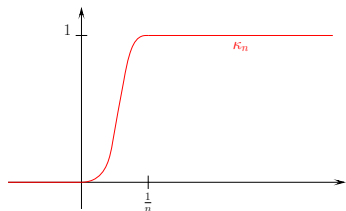
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We approximate its solution by the solutions to the SDEs

$$\begin{aligned} dx_n(t) &= \lambda(1 - \kappa_n^2(x_n(t)))dt + \kappa_n(x_n(t))dw(t), \\ x_n(0) &= x_0. \end{aligned}$$

which have non-negative strong solutions $x_n(t) \geq 0$.



$$\begin{aligned} \kappa_n(y) &\rightarrow \mathbb{I}_{\{y>0\}}, \\ 1 - \kappa_n^2(y) &\rightarrow 1 - \mathbb{I}_{\{y>0\}}^2 = \mathbb{I}_{\{y=0\}} \end{aligned}$$

for $y \geq 0$, as $n \rightarrow \infty$.

Problem of approximation

One can show that $\{x_n, n \geq 1\}$ is tight in $C[0, T]$ and $\{\kappa_n^2(x_n), n \geq 1\}$ is tight in $L^2[0, T]$ in weak topology

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$x_n \rightarrow x$ in $C[0, T]$ and $\kappa_n^2(x_n) \rightarrow \rho^2$ in $L_2[0, T]$ in weak t.

along a subsequence.

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$$M_n(t) := x_n(t) - x_0 + \int_0^t \lambda(1 - \kappa_n^2(x_n(s))) ds$$

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$$M(t) := x(t) - x_0 + \int_0^t \lambda \mathbb{I}_{\{x(s)=0\}} ds$$

$$[M_n]_t = \int_0^t \kappa_n^2(x_n(s)) ds \not\rightarrow \int_0^t \mathbb{I}_{\{x(s)>0\}} ds$$

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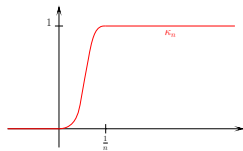
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Why $\rho^2(s) = \mathbb{I}_{\{x(s) > 0\}}$?

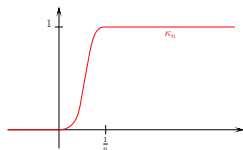
Two observations

- $\kappa_n^2(y_n) \not\rightarrow \mathbb{I}_{\{y>0\}}$ as $y_n \rightarrow y$.



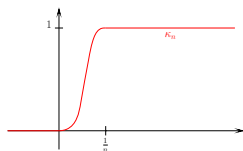
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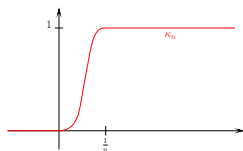
- If x is a continuous non-negative semimartingale with q.v.

$$[x]_t = \int_0^t \sigma^2(s) ds,$$

then $[x]_t = \int_0^t \mathbb{I}_{\{x(s)>0\}} \sigma^2(s) ds$.

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Proof.

$$\begin{aligned} \int_0^t \sigma^2(s) \mathbb{I}_{\{x(s)=0\}} ds &= \int_0^t \mathbb{I}_{\{0\}}(x(s)) d[x]_s \\ &= \int_{-\infty}^{+\infty} \mathbb{I}_{\{0\}}(y) L_t^y dx = 0, \end{aligned}$$

where L_t^y is the local time of x at y .

Identification of quadratic variation

Remind

$$M_n(t) := x_n(t) - x_0 + \int_0^t \lambda(1 - \kappa_n^2(x_n(s))) ds$$

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Therefore,

$$\begin{aligned} [x]_t &= [M]_t = \int_0^t \rho^2(s) ds = \int_0^t \mathbb{I}_{\{x(s) > 0\}} \rho^2(s) ds \\ &= \lim_n \int_0^t \mathbb{I}_{\{x(s) > 0\}} \kappa_n^2(x_n(s)) ds = \int_0^t \mathbb{I}_{\{x(s) > 0\}} ds \end{aligned}$$

Proof of existence of solution to sticky-reflected SHE

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \lambda \mathbb{I}_{\{X_t=0\}} + \mathbb{I}_{\{X_t>0\}} Q \dot{W}_t$$

Discrete equation

We discretize only the space variable $u \in [0, 1]$ by $\frac{k}{n}$, $k = 1, \dots, n$.
Set $\pi_k^n = \mathbb{I}_{[\frac{k-1}{n}, \frac{k}{n})}$ and define

$$w_k(t) := \sqrt{n} \int_0^t \int_0^1 (Q\pi_k^n)(u) W(du, ds)$$

Consider the following SDE

$$dx_k(t) = \frac{1}{2} \Delta^n x_k(t) dt + \mathbb{I}_{\{x_k(t)=0\}} dt + \sqrt{n} \mathbb{I}_{\{x_k(t)>0\}} dw_k(t), \quad k = 1, \dots, n,$$

with $x_0(t) = x_{n+1}(t) = 0$ and $\Delta^n x_k = n^2 (x_{k+1} + x_{k-1} - 2x_k)$

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Set

$$X_t^n(u) = x_k(t), \quad \frac{k-1}{n} \leq u < \frac{k}{n}, \quad u \in [0, 1].$$

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$$\text{with } x_0(t) = x_{n+1}(t) = 0 \quad \text{and} \quad \Delta^n x_k = n^2 (x_{k+1} + x_{k-1} - 2x_k)$$

Set

$$X_t^n(u) = x_k(t), \quad \frac{k-1}{n} \leq u < \frac{k}{n}, \quad u \in [0, 1].$$

Remark that $X^n \geq 0$.

Convergence result

For every $\varphi \in \mathcal{C}^2[0, 1]$ with $\varphi(0) = \varphi(1) = 0$,

$$M_t^{n,\varphi} := \langle X_t^n, \varphi \rangle - \langle X_0^n, \varphi \rangle - \frac{1}{2} \int_0^t \langle X_s^n, \tilde{\Delta}^n \varphi \rangle ds - \lambda \int_0^t \langle \mathbb{I}_{\{X_s^n=0\}}, \varphi \rangle ds$$

is a continuous martingale with quadratic variation

$$[M^{n,\varphi}]_t = \int_0^t \|\mathbb{Q}(\mathbb{I}_{\{X_s^n>0\}}\varphi)\|^2 ds$$

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$$[M^{n,\varphi}]_t = \int_0^t \|Q(\mathbb{I}_{\{X_s^n > 0\}} \varphi)\|^2 ds \rightarrow \int_0^t \|Q(\sigma_s \varphi)\|^2 ds = [M^\varphi]_t$$

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Equivalently

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \lambda(1 - \sigma_t) + \sigma_t Q \dot{W},$$

$$X_t(0) = X_t(1) = 0, \quad X_0(u) = g(u).$$

Identification of coefficient σ

Proposition

Let X solves the equation

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + a_t + \sigma_t Q \dot{W},$$

$$X_t(0) = X_t(1) = 0, \quad X_0(u) = g(u)$$

and $X \geq 0$. Then $\sigma_t = \mathbb{I}_{\{X_t > 0\}} \sigma_t$.

Identification of the coefficients

We come back to our equation with undefined coefficients:

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \lambda(1 - \sigma_t) + \sigma_t Q \dot{W},$$

$$X_t(0) = X_t(1) = 0, \quad X_0(u) = g(u), \quad X_t \geq 0.$$

By the previous proposition,

$$\sigma_t(u) = \mathbb{I}_{\{X_t(u) > 0\}} \sigma_t(u) = \lim_n \mathbb{I}_{\{X_t(u) > 0\}} \mathbb{I}_{\{X_t^n(u) > 0\}} = \mathbb{I}_{\{X_t(u) > 0\}}$$

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Idea of proof of the key proposition

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and $X \geq 0$. Then a.s. $\sigma_t = \mathbb{I}_{\{X_t > 0\}} \sigma_t$ for t -a.e.

Proof

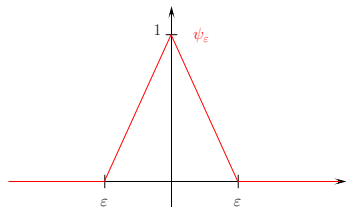
Analog of Ito's formula applied to F_ε :

$$\begin{aligned}\langle F_\varepsilon(X_t) - F_\varepsilon(X_0), 1 \rangle &= -\frac{1}{2} \int_0^t \langle F_\varepsilon''(X_s) \dot{X}_s, \dot{X}_s \rangle ds + \int_0^t \langle F_\varepsilon'(X_s), a_s \rangle ds \\ &\quad + \frac{1}{2} \int_0^t \langle Q[\sigma_s F_\varepsilon''(X_s) \cdot], Q[\sigma_s \cdot] \rangle_{HS} ds + M_{F_\varepsilon}(t),\end{aligned}$$

where

$$F_\varepsilon(x) := \int_{-\infty}^x \int_{-\infty}^y \psi_\varepsilon(r) dy dr,$$

$$0 \leq F_\varepsilon'(x) \leq 2\varepsilon, \quad F_\varepsilon''(x) \rightarrow \mathbb{I}_{\{0\}}(x)$$



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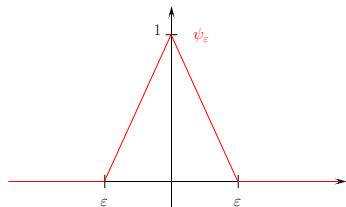
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Hence all green terms $\rightarrow 0$ and the red term $\rightarrow \int_0^t \langle Q[\sigma_s \mathbb{I}_{\{X_s=0\}} \cdot], Q[\sigma_s \cdot] \rangle_{HS} ds$

Proof

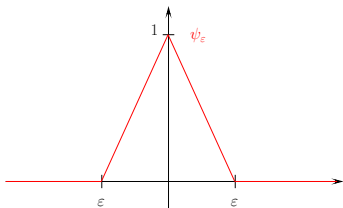
Analog of Ito's formula applied to F_ε :

$$\begin{aligned}\langle F_\varepsilon(X_t) - F_\varepsilon(X_0), 1 \rangle &= -\frac{1}{2} \int_0^t \langle F_\varepsilon''(X_s) \dot{X}_s, \dot{X}_s \rangle ds + \int_0^t \langle F_\varepsilon'(X_s), a_s \rangle ds \\ &\quad + \frac{1}{2} \int_0^t \langle Q[\sigma_s F_\varepsilon''(X_s) \cdot], Q[\sigma_s \cdot] \rangle_{HS} ds + M_{F_\varepsilon}(t),\end{aligned}$$

where

$$F_\varepsilon(x) := \int_{-\infty}^x \int_{-\infty}^y \psi_\varepsilon(r) dy dr,$$

$$0 \leq F_\varepsilon'(x) \leq 2\varepsilon, \quad F_\varepsilon''(x) \rightarrow \mathbb{I}_{\{0\}}(x)$$



Hence all green terms $\rightarrow 0$ and the red term $\rightarrow \int_0^t \langle Q[\sigma_s \mathbb{I}_{\{X_s=0\}} \cdot], Q[\sigma_s \cdot] \rangle_{HS} ds = 0$

\implies We can replace σ_s by $\mathbb{I}_{\{X_s > 0\}} \sigma_s$

Open problem and references

Open problems:

- Is a solution to the equation unique?
- Does the solution of the equation with the identity operator Q exists?
- What is the invariant measure for the dynamics?
- How much time does the equation spend at zero?



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Ukrain. Math. J., Vol. 72, no. 9, 2021



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to appear in *Annales de l'Institut Henri Poincaré*

Thank you!