

# Sticky-reflected stochastic heat equation driven by colored noise

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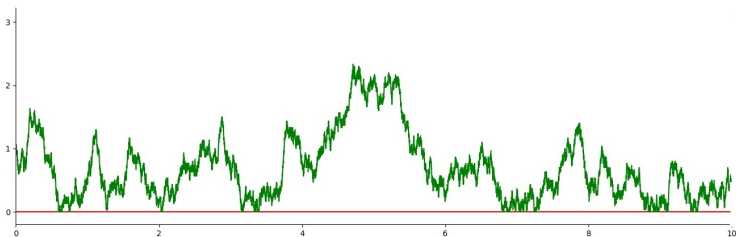
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Changchun – 2021

# Introduction of the equation

# Sticky-reflected Brownian motion

$$dx(t) = \lambda \mathbb{I}_{\{x(t)=0\}} dt + \mathbb{I}_{\{x(t)>0\}} dw(t),$$
$$x(0) = x_0 \geq 0,$$

where  $\lambda > 0$  and  $w$  is an 1-dim Brownian motion.

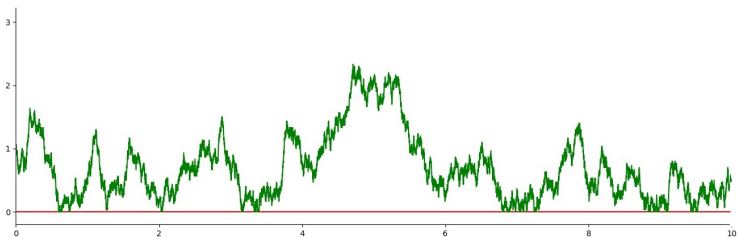


The equation admits only a **weak solution** which is **unique in law**  
(Engelbert and Peskir, 2014)

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# Stochastic heat equation

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \dot{W}_t, \quad t > 0, \quad u \in (0, 1),$$
$$X_0 = g, \quad X_t(0) = X_t(1) = 0,$$

where  $\dot{W}$  is a space-time white noise and  $g \in C[0, 1]$ .

## Definition of weak solution

A continuous process  $X : [0, \infty) \times [0, 1] \rightarrow \mathbb{R}$  is called a **weak solution** to the SHE if for any  $\varphi \in C^2[0, 1]$  with  $\varphi(0) = \varphi(1) = 0$

$$M_t^\varphi := \langle X_t, \varphi \rangle - \langle X_0, \varphi \rangle - \frac{1}{2} \int_0^t \langle X_s, \varphi'' \rangle ds$$

is a martingale with quadratic variation

$$[M^\varphi]_t = \int_0^t \|\varphi\|_{L^2}^2 ds,$$

where  $\langle X_t, \varphi \rangle = \int_0^1 X_t(u) \varphi(u) du$ .

(Well-posedness – Funaki, 1983)

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$$\begin{aligned} dx(t) &= dw(t), \\ x(0) &= x_0 \geq 0, \end{aligned}$$

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**Reflected SHE** (D. Nulart and É. Pardoux '92)

$$\begin{aligned}\frac{\partial X_t}{\partial t} &= \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + L_t + \dot{W}_t \\ X_0 &= g \geq 0, \quad X_t(0) = X_t(1) = 0, \\ \int_0^\infty \int_0^1 X_t(u) dL_t(u) &= 0, \quad X_t \geq 0.\end{aligned}$$

There exists a unique continuous process  $X : [0, 1] \times [0, \infty) \rightarrow \mathbb{R}$  and a measure (local time)  $L$  on  $[0, 1] \times [0, \infty)$  satisfying the reflected SHE.

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# Formulation of the main result

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where  $Q$  is non-negative definite self-adjoint Hilbert-Schmidt operator in  $L_2[0, 1]$

### Solution to sticky-reflected SHE

A continuous process  $X : [0, \infty) \times [0, 1] \rightarrow \mathbb{R}$  is called a **weak solution** to the sticky-reflected SHE if for any  $\varphi \in C^2[0, 1]$  with  $\varphi(0) = \varphi(1) = 0$

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# Formulation of the main result

Let  $\{e_k, k \geq 1\}$  and  $\{\mu_k, k \geq 1\}$  be eigenvectors and eigenvalues of  $Q$ . Define

$$\chi^2 := \sum_{k=1}^{\infty} \mu_k^2 e_k^2.$$

**Theorem** K. 2021

If  $\chi^2 > 0$  a.e., then the sticky-reflected SHE admits a weak solution.

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If  $\chi^2 > 0$  a.e., then the sticky-reflected SHE admits a weak solution.

# Meaning of assumption $\chi^2 > 0$

The equation

$$\begin{aligned} dx(t) &= \lambda \mathbb{I}_{\{x(t)=0\}} dt + \mathbb{I}_{\{x(t)>0\}} dw(t) \\ x(0) &= 0 \end{aligned}$$

has **no solution**

$\chi^2 = \sum_{k=1}^{\infty} \mu_k^2 e_k^2 > 0$  means that the solution  $X$  to the equation

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \lambda \mathbb{I}_{\{X_t=0\}} + \mathbb{I}_{\{X_t>0\}} Q \dot{W}_t$$

feels a noise at **any** point of  $[0, 1]$ .

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Description of the idea of construction of solution

using the equation

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# Step I. Approximation sequence

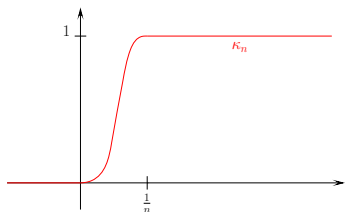
Consider the SDE for sticky-reflected BM:

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We approximate its solution by the solutions to the SDE

$$\begin{aligned} dx_n(t) &= \lambda(1 - \kappa_n^2(x_n(t)))dt + \kappa_n(x_n(t))dw(t), \\ x_n(0) &= x_0. \end{aligned}$$

which have non-negative strong solutions  $x_n(t) \geq 0$ .



$$\begin{aligned} \kappa_n(y) &\rightarrow \mathbb{I}_{\{y>0\}}, \\ 1 - \kappa_n^2(y) &\rightarrow 1 - \mathbb{I}_{\{y>0\}}^2 = \mathbb{I}_{\{y=0\}} \end{aligned}$$

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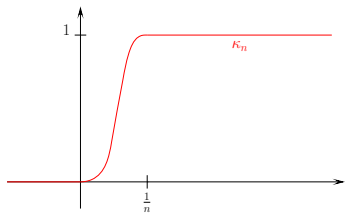
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# Problem of approximation

Once can show that  $\{x_n, n \geq 1\}$  is tight in  $C[0, \infty)$   $\implies$

$$x_n \rightarrow x \quad \text{in } C[0, \infty)$$

along a subsequence.

But

$$\begin{array}{ccc} x_n(t) = x_0 + \int_0^t \lambda(1 - \kappa_n^2(x_n(s))) ds + \int_0^t \kappa_n(x_n(s)) dw(s), & & \\ \downarrow & \downarrow & \downarrow \\ x(t) = x_0 + \int_0^t \lambda \mathbb{I}_{\{x(s)=0\}} ds + \int_0^t \mathbb{I}_{\{x(s)>0\}} dw(s) & & \end{array}$$

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## Step II. Convergence in an appropriate space

$$x_n(t) = x_0 + \int_0^t \lambda(1 - \kappa_n^2(x_n(s)))ds + \int_0^t \kappa_n(x_n(s))dw(s),$$

Using tightness argument, one has

$$x_n(t) \rightarrow x(t)$$

$$a_n(t) := \int_0^t \lambda(1 - \kappa_n^2(x_n(s)))ds \rightarrow a(t)$$

$$\eta_n(t) := \int_0^t \kappa_n(x_n(s))dw(s) \rightarrow \eta(t)$$

$$[\eta_n]_t = \int_0^t \kappa_n^2(x_n(s))ds \rightarrow \rho(t)$$

in  $C[0, \infty)$  in distribution along a subsequence.

## Step III. Properties of the limit process

$$x_n(t) \rightarrow x(t), \quad a_n(t) := \int_0^t \lambda(1 - \kappa_n^2(x_n(s))) ds \rightarrow a(t)$$
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We remark that

- $x(t) = x_0 + a(t) + \eta(t) \geq 0$
- $\eta$  is a continuous martingale
- $[\eta(t)]_t = \rho(t)$
- $\kappa_n^2(x_n)$  is tight in the weak topology of  $L_2[0, T]$ , therefore,

$$\kappa_n^2(x_n) \rightarrow \dot{\rho} \in L_2[0, T] \quad \text{and} \quad \rho(t) = \int_0^t \dot{\rho}(s) ds$$

- $a(t) = \lambda t - \lambda \rho(t) = \int_0^t \lambda(1 - \dot{\rho}(s)) ds$

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We remark that

- $x(t) = x_0 + a(t) + \eta(t) = x_0 + \int_0^t \lambda \mathbb{I}_{\{x(s)=0\}} ds + \int_0^t \mathbb{I}_{\{x(s)>0\}} d\tilde{w}(s)$
- $\eta$  is a continuous martingale
- $[\eta(t)]_t = \rho(t) = \int_0^t \mathbb{I}_{\{x(s)>0\}} ds$
- $\kappa_n^2(x_n)$  is tight in the weak topology of  $L_2[0, T]$ , therefore,

$$\kappa_n^2(x_n) \rightarrow \dot{\rho} \in L_2[0, T] \quad \text{and} \quad \rho(t) = \int_0^t \dot{\rho}(s) ds$$

- $a(t) = \lambda t - \lambda \rho(t) = \int_0^t \lambda(1 - \dot{\rho}(s)) ds = \int_0^t \lambda(1 - \mathbb{I}_{\{x(t)>0\}}) ds = \int_0^t \lambda \mathbb{I}_{\{x(s)=0\}} ds$

**We need to show that  $\dot{\rho}(s) = \mathbb{I}_{\{x(s)>0\}}$ !**

# Key observation

## Lemma

If  $x$  is a continuous **non-negative** semimartingale with q.v.

$$[x]_t = \int_0^t \sigma^2(s) ds,$$

then

$$\sigma^2(s) = \sigma^2(s) \mathbb{I}_{\{x(s) > 0\}} \quad s\text{-a.e.}$$

*Proof.*

$$\begin{aligned} \int_0^t \sigma^2(s) \mathbb{I}_{\{x(s)=0\}} ds &= \int_0^t \mathbb{I}_{\{0\}}(x(s)) d[x]_s \\ &= \int_{-\infty}^{+\infty} \mathbb{I}_{\{0\}}(x) L_t^x dx = 0, \quad t \geq 0 \end{aligned}$$

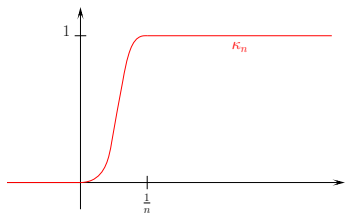
whre  $L_t^x$  is the local time of  $x$ .

# Step IV. Identification of quadratic variation

## Remind

- $x(t) = x_0 + a(t) + \eta(t) \geq 0$  is a continuous semimartingale
- $[x]_t = [\eta]_t = \int_0^t \dot{\rho}(s) ds$
- $\kappa_n^2(x_n) \rightarrow \dot{\rho}$  in a weak topology of  $L_2[0, 1]$  along a subsequence

Since  $\dot{\rho} = \dot{\rho} \mathbb{I}_{\{x(s) > 0\}}$  and



$$\kappa_n^2(y_n) \mathbb{I}_{\{y > 0\}} \rightarrow \mathbb{I}_{\{y > 0\}},$$

as  $y_n \rightarrow y$ , we get

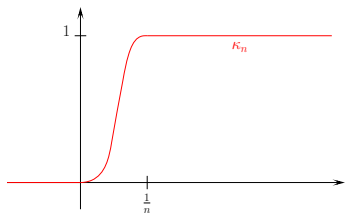
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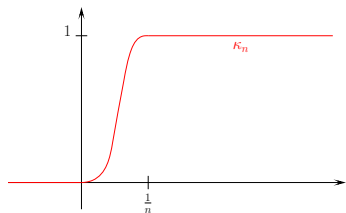
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Proof of existence of solution to  
sticky-reflected SHE

$$\frac{\partial X_t}{\partial t} = \frac{1}{2} \frac{\partial^2 X_t}{\partial u^2} + \lambda \mathbb{I}_{\{X_t=0\}} + \mathbb{I}_{\{X_t>0\}} Q \dot{W}_t$$

# Discrete equation

We discretize only the space variable  $u \in [0, 1]$  by  $\frac{k}{n}$ ,  $k = 1, \dots, n$ .

Set  $\pi_k^n = \mathbb{I}_{[\frac{k-1}{n}, \frac{k}{n})}$  and define

$$w_k(t) := \sqrt{n} \int_0^t \int_0^1 (Q\pi_k^n)(u) W(du, ds)$$

Consider the following SDE

$$dx_k(t) = \frac{1}{2} \Delta^n x_k(t) dt + \mathbb{I}_{\{x_k(t)=0\}} dt + \sqrt{n} \mathbb{I}_{\{x_k(t)>0\}} dw_k(t), \quad k = 1, \dots, n,$$

$$\text{with } x_0(t) = x_{n+1}(t) = 0 \quad \text{and} \quad \Delta^n x_k = n^2 (x_{k+1} + x_{k-1} - 2x_k)$$

Set

$$X_t^n(u) = x_k(t), \quad \frac{k-1}{n} \leq u < \frac{k}{n}, \quad u \in [0, 1].$$

Remark that  $X^n \geq 0$ .

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# Convergence result

For every  $\varphi \in \mathcal{C}^2[0, 1]$  with  $\varphi(0) = \varphi(1) = 0$ ,

$$\langle X_t^n, \varphi \rangle = \langle X_0^n, \varphi \rangle + \frac{1}{2} \int_0^t \langle X_s^n, \tilde{\Delta}^n \varphi \rangle ds + \int_0^t \langle \mathbb{I}_{\{X_s^n=0\}}, \varphi \rangle ds + B_\varphi^n$$

where  $B_\varphi^n$  is a continuous martingale with  $[B_\varphi^n]_t = \|\mathbb{Q}(\mathbb{I}_{\{X_t^n > 0\}} \varphi)\|^2$ .

There exists a subsequence  $n_k$ ,  $k \geq 1$ , and a continuous process  $X$  such that

- $X^{n_k}(u, t) \rightarrow X(u, t)$ ,  $\forall u, t$ ;
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Hence

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Equivalently

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# Identification of coefficient $\sigma$

## Proposition (K., 2020)

Let  $X$  solves the equation

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# Identification of the coefficients

By the previous proposition,

$$\sigma_t(u) = \mathbb{I}_{\{X_t(u) > 0\}} \sigma_t(u) = \lim_{k \rightarrow \infty} \mathbb{I}_{\{X_t(u) > 0\}} \mathbb{I}_{\{X_t^{n_k}(u) > 0\}} = \mathbb{I}_{\{X_t(u) > 0\}}$$

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# Idea of proof of the key proposition

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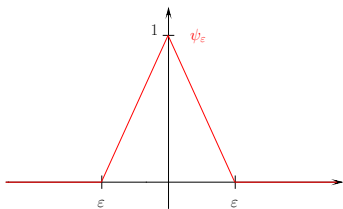
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where

$$F_\varepsilon(x) := \int_{-\infty}^x \int_{-\infty}^y \psi_\varepsilon(r) dy dr,$$

$$0 \leq F_\varepsilon'(x) \leq 2\varepsilon, \quad F_\varepsilon''(x) \rightarrow \mathbb{I}_{\{0\}}(x)$$



Hence all green terms  $\rightarrow 0$  and red term  $\rightarrow \int_0^t \langle Q[\sigma \mathbb{I}_{\{X_s=0\}} \cdot], Q[\sigma \cdot] \rangle_{HS} ds$

$\implies$  We can replace  $\sigma$  by  $\mathbb{I}_{\{X_s > 0\}} \sigma$

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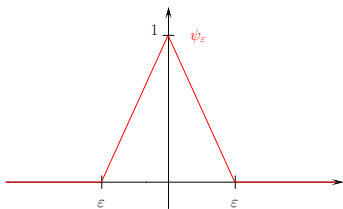
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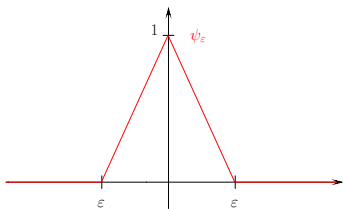
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$\implies$  We can replace  $\sigma$  by  $\mathbb{I}_{\{X_s > 0\}} \sigma$

# Open problem and references

## Open problems:

- Is a solution to the equation unique?
- Does the solution of the equation with the identity operator  $Q$  exists?
- What is the invariant measure for the dynamics?
- How much time does the equation spend at zero?



Vitalii Konarovskiy,  
Sticky-Reflected Stochastic Heat Equation Driven by Colored Noise  
*Ukrain. Math. J.*, Vol. 72, no. 9, 2021  
(arXiv:2005.11773)



Vitalii Konarovskiy,  
Coalescing-Fragmentating Wasserstein Dynamics: particle approach  
(arXiv:1711.03011)

Thank you for your attention!